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# **UNIPLUS**

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# 2.1 CAN-bus OPERATING INSTRUCTIONS

## SYSTEM DESCRIPTION

The electro-hydraulic control system used on the UNIPLUS is a CAN-bus system where all the control signals are carried by one pair of wires. The 12 Volt, 30 Amp power supply is taken directly from the tractor battery to the machine fuses, as the incab power plugs on some tractors may not be capable of supplying an adequate amperage. Additional wires are used to power the control box and an auxiliary power supply.

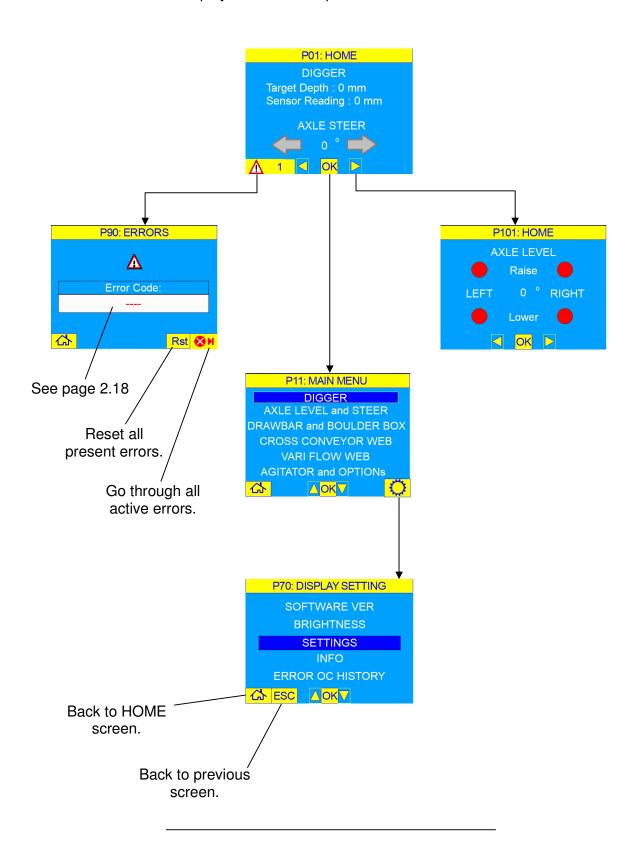
The system comprises of the control fascia which is connected to the input circuit board. The control box screen displays an overall illustration of the system and allows access to select and set operating parameters. The screen also gives access to a service menu which will allow the status of each function to be displayed.

On the machine, the power and control wires are taken onto a distribution board which allows the connection of the various control sensors and the fuses which cover all the power outputs. From the distribution board the master processor module is connected into the wiring loom which connects all the individual hydraulic valves.

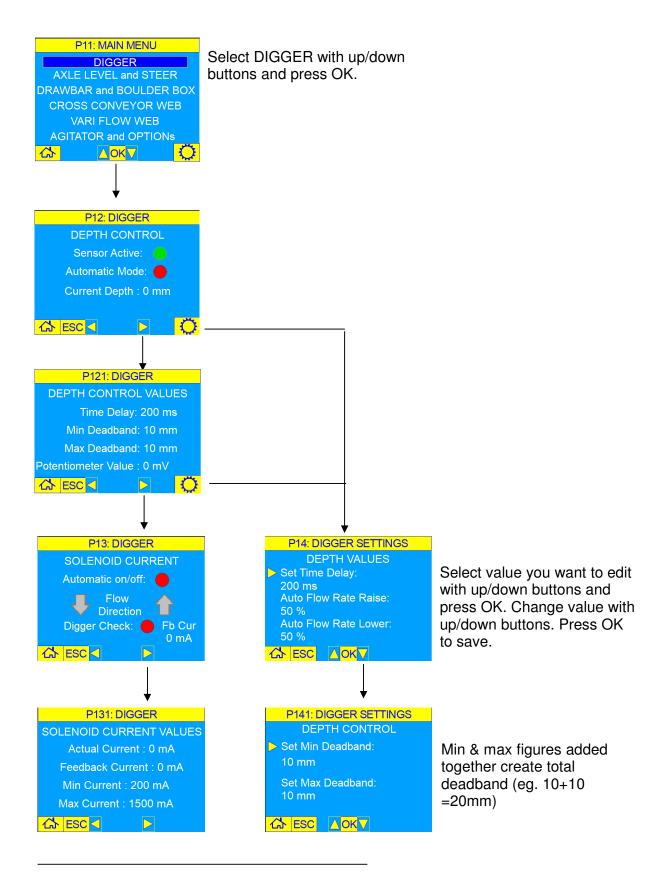
The switches on the control panel are designed to cover all build options. Depending on the specification of the machine, some functions will not be active.

#### **HOME SCREEN**

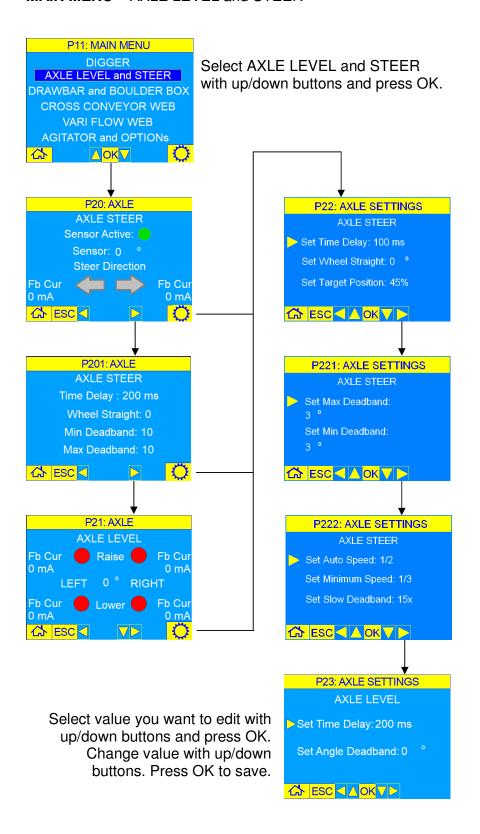
HOME screen is displayed after start-up.



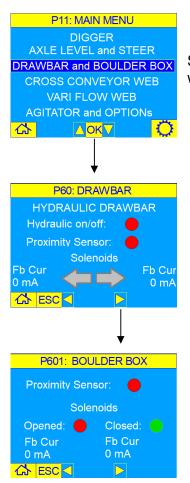
#### **MAIN MENU** - DIGGER



## MAIN MENU - AXLE LEVEL and STEER

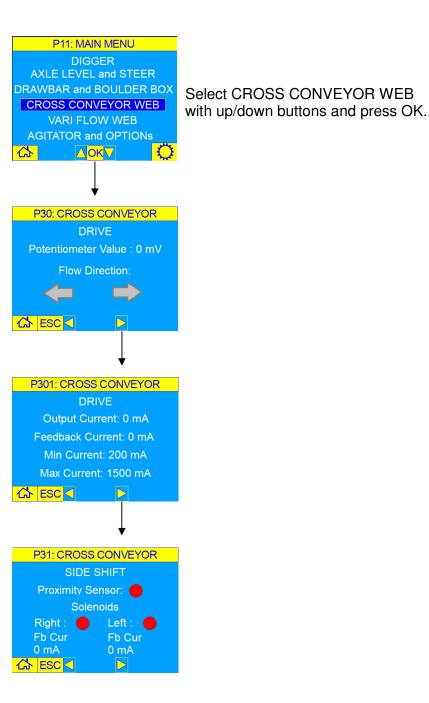


## MAIN MENU - DRAWBAR and BOULDER BOX



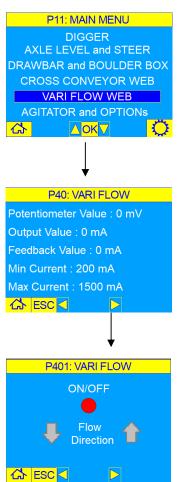
Select DRAWBAR and BOULDER BOX with up/down buttons and press OK.

#### MAIN MENU - CROSS CONVEYOR WEB



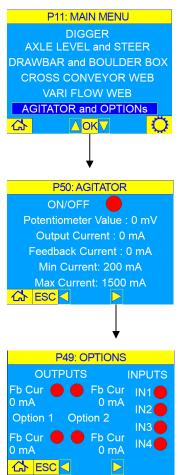
# 2.7 CAN-bus OPERATING INSTRUCTIONS

### MAIN MENU - VARI FLOW WEB



Select VARI FLOW WEB with up/down buttons and press OK.

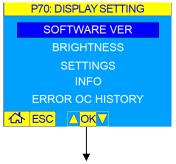
#### **MAIN MENU** – AGITATOR and OPTIONS



Select AGITATOR and OPTIONS with up/down buttons and press OK.

# **CAN-bus OPERATING INSTRUCTIONS**

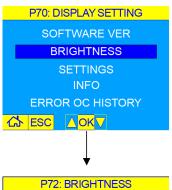
#### **DISPLAY SETTING** – SOFTWARE VERSION



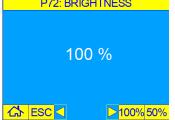
Select SOFTWARE VER with up/down buttons and press OK.



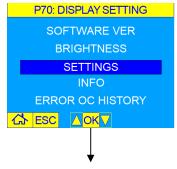
# **DISPLAY SETTING** – BRIGHTNESS



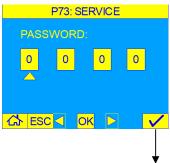
Select BRIGHTNESS with up/down buttons and press OK.



## **DISPLAY SETTING** – DEALER SETTINGS



Select SETTINGS with up/down buttons and press OK.

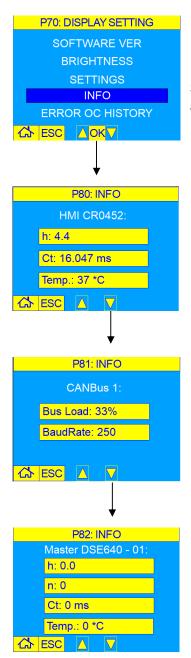


Enter password to access dealer settings in the SERVICE MENU. (Contact Standen Engineering).



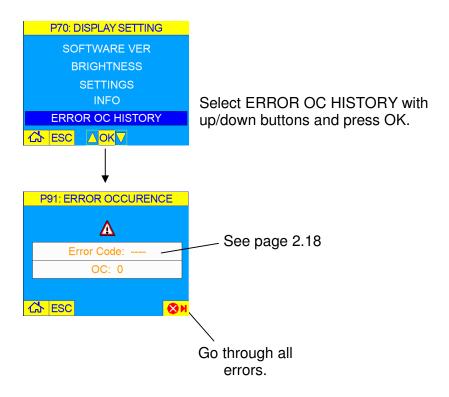
# 2.11 CAN-bus OPERATING INSTRUCTIONS

### **DISPLAY SETTING** – INFORMATION



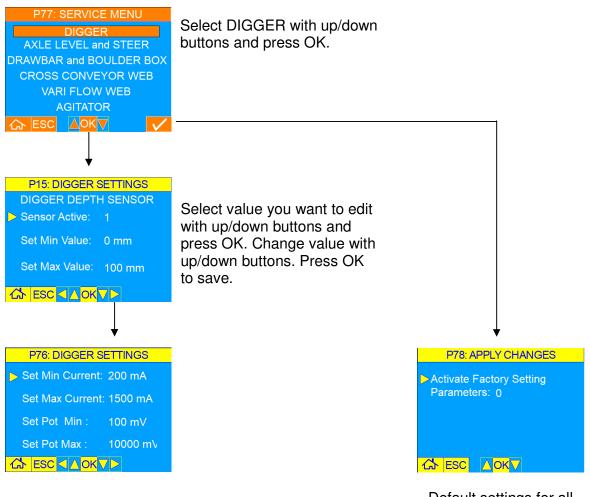
Select INFO with up/down buttons and press OK.

# **DISPLAY SETTING** – ERROR OCCURRENCE HISTORY



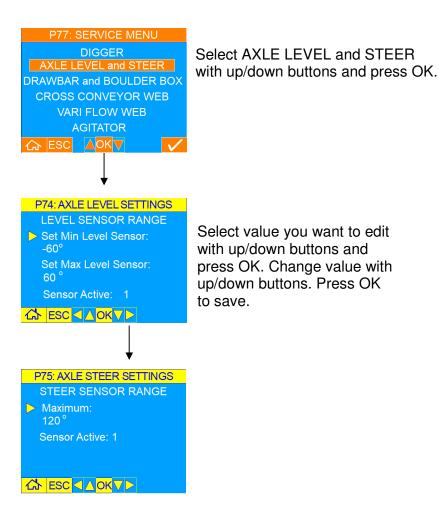
# 2.13 CAN-bus OPERATING INSTRUCTIONS

## **SERVICE MENU** – DIGGER (dealer settings)



Default settings for all machine parameters set to 1.

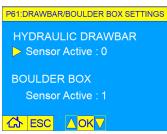
**SERVICE MENU** – AXLE LEVEL and STEER (dealer settings)



**SERVICE MENU** – DRAWBAR and BOULDER BOX (dealer settings)

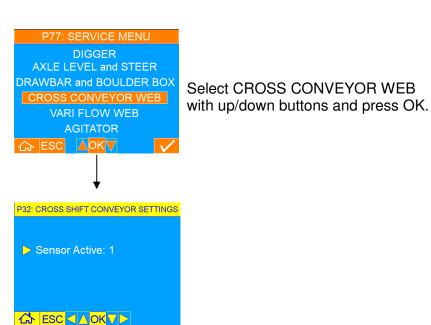


Select DRAWBAR and BOULDER BOX with up/down buttons and press OK.



Select value you want to edit with up/down buttons and press OK. Change value with up/down buttons. Press OK to save.

**SERVICE MENU** – CROSS CONVEYOR WEB (dealer settings)

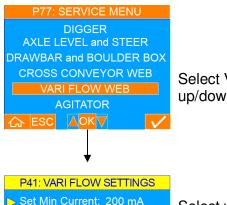




Select value you want to edit with up/down buttons and press OK. Change value with up/down buttons. Press OK to save.

# 2.17 CAN-bus OPERATING INSTRUCTIONS

### **SERVICE MENU** – VARI FLOW WEB (dealer settings)



Select VARI FLOW WEB with up/down buttons and press OK.

P41: VARI FLOW SETTINGS

Set Min Current: 200 mA

Set Max Current: 1500 mA

Set Pot Min: 100 mV

Set Pot Max: 10000 mV

Ch ESC AOKV

Select value you want to edit with up/down buttons and press OK. Change value with up/down buttons. Press OK to save.

## **SERVICE MENU** – AGITATOR (dealer settings)



Select AGITATOR with up/down buttons and press OK.



Select value you want to edit with up/down buttons and press OK. Change value with up/down buttons. Press OK to save.

# **ERROR CODES**

# STANDEN Uniplus Error Codes From 2021

Error code	Description	Wire Number
1000		
1001	VB Voltage below normal or shorted low	
1002	Can Network 1 loss of communication	
1003	Depth sensor	B17
1004	Digger Raise solenoid	В3
1005	Digger Lower solenoid	СЗ
1006	Digger Check solenoid	B27
1007	Digger potentiometer	
1008	Axle level sensor	B19
1009	Axle Level Raise left solenoid	B12
1010	Axle Level left-Lower check solenoid	C12
1011	Axle Level Raise right solenoid	B13
1012	Axle Level Lower right check solenoid	C13
1013	Axle Steer sensor	B18
1014	Axle Steer left solenoid	B25
1015	Axle Steer right solenoid	C25
1016	Vari flow web forward solenoid	C1
1017	Vari flow web reverse solenoid	B1
1018	Vari flow web potentiometer	
1019	Agitator solenoid	B34
1020	Agitator potentiometer	
1021	Cross Drive web left solenoid	B23
1022	Cross Drive web right solenoid	C23
1023	Cross Drive web potentiometer	
1024	Drawbar Right solenoid	B4
1025	Drawbar Left solenoid	C4
1026	Drawbar sensor	B15
1027	Cross Shift web left solenoid	C10
1028	Cross Shift web right solenoid	B10
1029	Boulder Box open solenoid	B2
1030	Boulder Box close solenoid	C2
1031	Boulder Box sensor	B14
1032	Loss of communication with Wurth device	
1033	Option1 output	C27
1034	Option2 output	B33
1035	Option3 output	C33
1036	Option4 output	B35
1037		
1038		

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